The Uintah Framework: A Unified Heterogeneous Task Scheduling and Runtime System

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Current and Past Uintah Applications



Uintah Data Parallelism

Uintah uses both data and task parallelism



Gird and Patches (Physical Domain)

- Structured Grid(Flows) + Particles System(Solids)
- Patch-based Domain
 Decomposition for Parallel Processing
- Adaptive Mesh Refinement
- Dynamic Load Balancing
 - Profiling + Forecasting Model
 - Parallel Space Filling Curves
 - Data Migration



Uintah Task Parallelism and Uintah Task Graph

Patch-based domain decomposition



User defines Uintah Tasks:

Serial code (call back functions)

Input and output variables

- Distributed: only creates tasks on local patches
- Framework analyzes task dependencies and creates TG
 - Automatic MPI message generation
 - Dynamic Task Execution (Data Driven Overlap)



Task Graph

NIVERSITY of Utah

Uintah Runtime System: How Uintah Runs Tasks

- Memory Manager: Uintah Data Warehouse (DW)
 - Variable dictionary (hashed map from: Variable Name, Patch ID, Material ID keys to memory)
 - Provide interfaces for tasks to
 - Allocate variables
 - Put variables into DW
 - Get variables from DW
 - Automatic Scrubbing (garbage collection)
 - Checkpointing & Restart (data archiver)
- Task Manager: Uintah schedulers
 - Decides when and where to run tasks
 - Decides when to process MPI



Thread/MPI Scheduler (De-centralized)



- Memory saving: reduce ghost copies and metadata
- Work stealing inside node: all threads directly pull tasks from task queues, no on-node MPI
- Full Overlapping: All threads process MPI sends/receives and execute tasks
- Use lock-free data structure (avoid locking overhead) UNITY of UNITY

Scalability Improvement



Original Dynamic MPI-only Scheduler De-centralized MPI/Thread Hybrid Scheduler

(with Lock-free Data Warehouse)

- Achieve much better CPU Scalability
- 95% weak scaling efficiency on 256K cores (Jaguar XK6)
- Use GPUs to accelerate Uintah Components



Uintah GPU Task Management

Framework manages all CUDA data movement (NOT inside task)

- Use Asynchronous API
- Automatically generate CUDA stream for each dependency
- Concurrently execute kernels and memcopies
- Prefetching data before task kernel execute
- Multi-GPU support

 Two call back functions for both CPU version and GPU version:
 Compatible for non-GPU nodes



Stages of GPU task in Uintah runtime



Multistage Task Queues Architecture



Fully Overlap computation with PCIe transfers and MPI communication



Unified Heterogeneous Scheduler & Runtime





GPU RMCRT Speedup Results (Multi-Node)

All CPU cores vs Single GPU

	Nodes	CPU(sec) CPU+GP (sec)		Speedup (x)	
Keeneland Initial Delivery System	1	319.769	8.49714	38 X	
	2	163.773	7.68571	21X	
	4	70.0943	4.80571	14X	
	8	39.5686	2.62857	15X	
	16	20.2414	3.52857	6X	7
	32	18.8043	2.73857	6X	-*
	64	9.11571	2.95714	3X	

CPU Core – (2) Intel Xeon 6-core X5660 (Westmere) @2.8GHz
 GPU – (1) Nvidia M2090

* GPU implementation quickly runs out of work, scaling breaks down



Scaling Comparisons



- Uintah strong scaling results when using:
 - MPI-only
 - Multi-threaded MPI
 - Multi-threaded MPI w/ GPU
- Two Problems:
 - AMR MPMICE

Nearest neighbors communication 3.62 billion particles

GPU-enabled ray tracer
 All-to-all communication
 100 rays per cell 128³ cells

Uintah Scaling Overview

- MPI only AMR MPMICE: N=6144 CPU cores; Largest = 98K CPU cores
- Thread/MPI AMR MPMICE: N=8192 CPU cores; Largest=256K CPU cores
- Thread/MPI RayTracing: N=16 CPU cores; Largest=1024 CPU cores
- Thread/MPI/GPU RayTracing: N=16 CPU and 1 GPU; Largest=1024 CPU and 64 GPU



Future Work

Scheduler – Infrastructure

- GPU affinity for multi socket/GPU nodes
- Support Intel MIC (Xeon Phi) offload-mode
- PETSc GPU interface utilization
- Mechanism to dynamically determine whether to run GPU or CPU version task
- Optimize GPU codes for Nvidia Kepler
 CUDA 5.0 Dynamic Parallelism
 - GPU sub-scheduler







Alstom Clean Coal Boiler Simulation Monte Carlo Ray Tracing on GPU, Flow simulation on CPU



Software Homepage http://www.uintah.utah.edu/





Using GPUs in Energy Applications



- ARCHES Combustion Component
 - Alstom Clean Coal Boiler Problem
- Need to approximate radiation transfer equation
- Reverse Monte Carlo Ray Tracing (RMCRT)



- Rays mutually exclusive traced simultaneously
 Ideal for SIMD parallelization of GPU
- Offload Ray Tracing and RNG to GPU(s)
 - CPU cores can perform other computation



Performance Comparisons Master-Slave Model vs. Unified

Execution Times – CPU Only										
#Cores	2	4		8	16	32				
Master Slave	57.28	3 20.	72	9.40	4.81	2.95				
Unified	29.79) 15.	70	8.23	4.54	2.78				
Execution Times – With GPU										
#Cores	2	4	6	8	10	12				
Master Slave	4.55	4.09	3.95	3.68	3 3.64	3.34				
Unified	3.82	3.52	3.09	2.90) 2.50	2.09				

CPU Problem: Combined MPMICE problem using AMR

Run on single Cray XE6 node with two 16-core AMD Opteron 6200 Series (Interlagos cores @2.6GHz) processors

GPU Problem: Reverse Monte Carlo Ray Tracer

Run on a single 12-core heterogeneous node (two Intel Xeon X5650 processors each with Westmere 6-core @2.67GHz, (2) Nvidia Tesla C2070 GPUs and (1) Nvidia GeForce 570 GTX GPU)

