

# Puffin: An Embedded Domain-Specific Language for Existing Unstructured Hydrodynamics Codes

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Christopher Earl



# Overview

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Puffin is an experimental C++98 template meta-programming language, targeting:

Unstructured hydrodynamics calculations  
Initially LULESH 2.0, a Lawrence Livermore proxy application

Multiple architectures  
Currently, just supports single-thread CPU  
Eventually, multi-thread CPU, GPU, and Xeon Phi

Existing (C++) projects / codes

# Adding Puffin to an Existing Project

In relevant C++ header and source files, add:

```
#include <Puffin.h>
```

To the existing build system, add dependencies to `Puffin*.h` (16 files)

Future additions may require optional dependencies

For example, NVIDIA's `nvcc` will be required for GPU execution

# Puffin Aspects

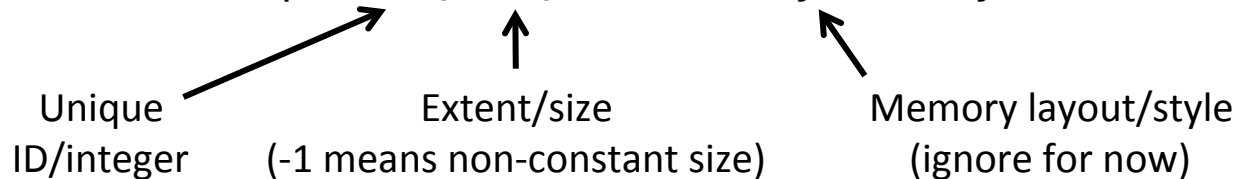
Puffin's basic "space" abstraction is an **aspect**:

Data/memory "space:" dimensions of arrays

Iteration "space:" Loop dimensions

Aspects are user/project defined:

```
typedef PuffinAspect<0, 3, PuffinStyleContainer> DimAspect;  
typedef PuffinAspect<1, -1, PuffinStyleArray> NodeAspect;  
typedef PuffinAspect<2, -1, PuffinStyleArray> ElemAspect;
```



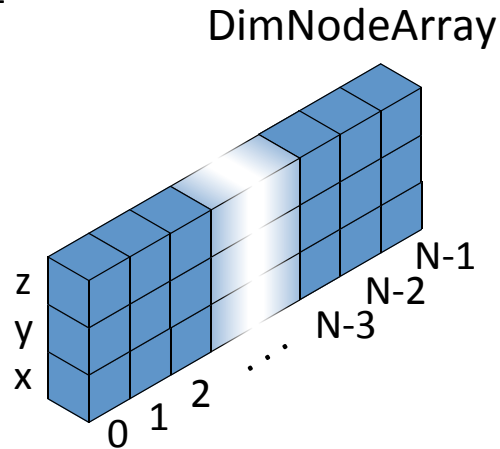
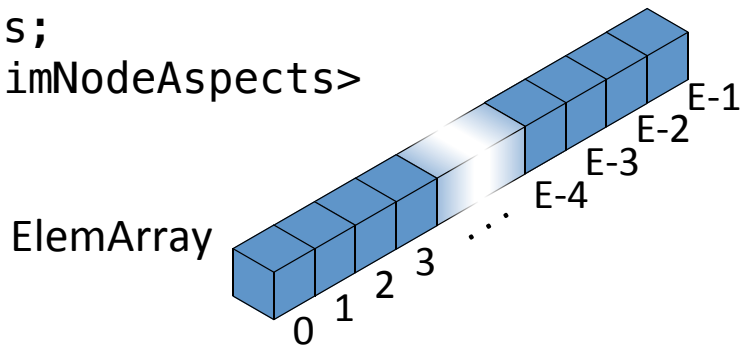
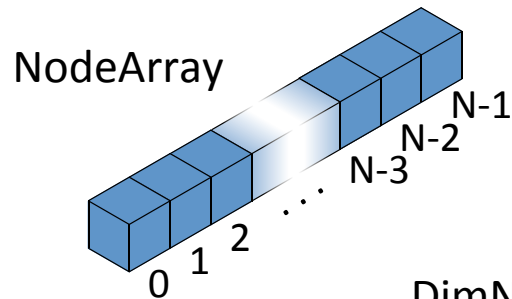
# Puffin Arrays

## Puffin's Basic Variables

### Single- and multiple-aspect arrays:

```
typedef PuffinArray<NodeAspect>  
NodeArray;  
typedef PuffinArray<ElemAspect>  
ElemArray;
```

```
typedef PuffinAspects<DimAspect, NodeAspect>  
DimNodeAspects;  
typedef PuffinArray<DimNodeAspects>  
DimNodeArray;
```



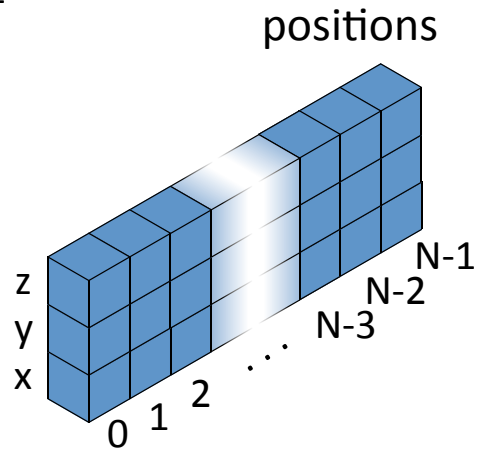
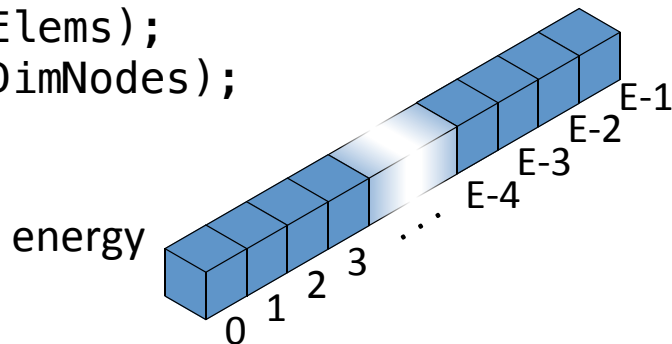
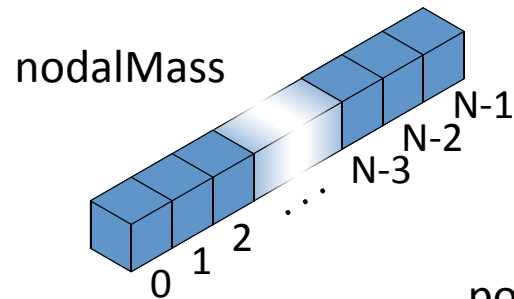
# Puffin Arrays

## Puffin's Basic Variables

### Declaration of Puffin arrays:

```
NodeAspect      Nodes      (N);  
ElemAspect     Elem       (E);  
DimAspect      Dim;  
DimNodeAspects DimNodes(Dim, Nodes);
```

```
NodeArray      nodalMass(Nodes);  
ElemArray      energy  (Elems);  
DimNodeArray   positions(DimNodes);
```



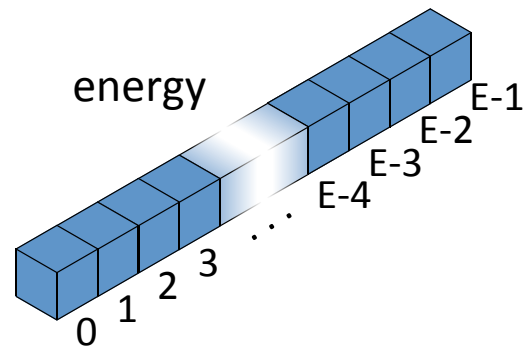
# Puffin Provided Arrays

## To use existing arrays with Puffin:

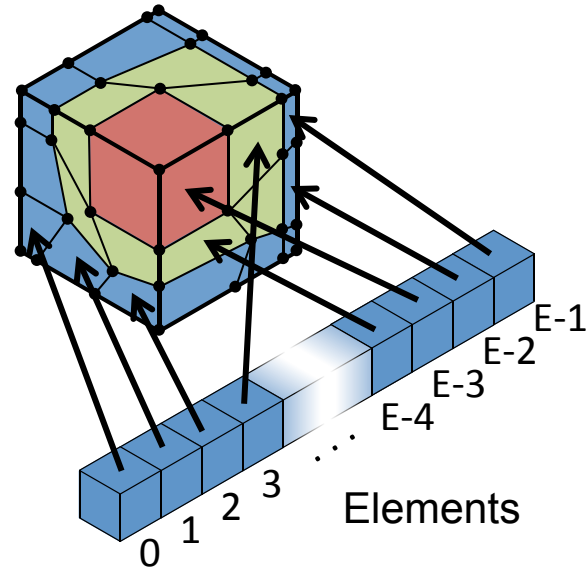
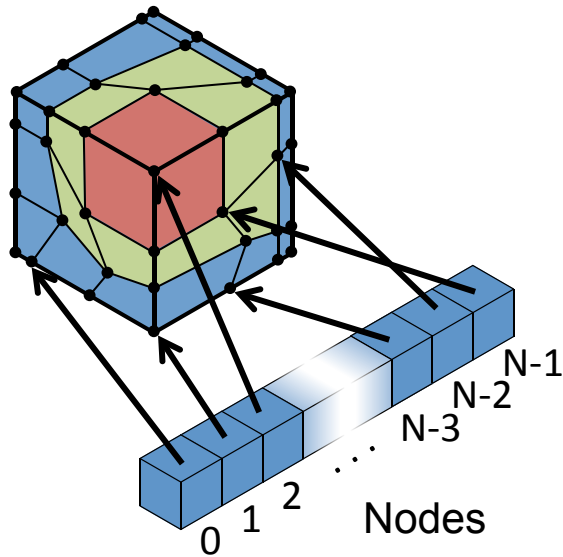
```
typedef PuffinProvidedArray<ElemAspect>  
ElemProvidedArray;
```

```
double* m_energy = ...; //lulesh allocation
```

```
ElemProvidedArray energy(Elems, m_energy);
```



# Unstructured Meshes



Order of values (nodes, elements, etc.) in arrays need not correspond to any ordering of simulated space.



# Single Assignment Example

## Acceleration calculation in LULESH 2.0:

```
for (Index_t i = 0; i < N; ++i) {  
    domain.xdd(i) = domain.fx(i) / domain.nodalMass(i);  
    domain.ydd(i) = domain.fy(i) / domain.nodalMass(i);  
    domain.zdd(i) = domain.fz(i) / domain.nodalMass(i);  
}
```

↑ acceleration                      ↑ force                      ↑ mass

# Single Assignment Example

## Acceleration calculation in LULESH 2.0:

```
for (Index_t i = 0; i < N; ++i) {  
    domain.xdd(i) = domain.fx(i) / domain.nodalMass(i);  
    domain.ydd(i) = domain.fy(i) / domain.nodalMass(i);  
    domain.zdd(i) = domain.fz(i) / domain.nodalMass(i);  
}
```

Diagram illustrating the acceleration calculation in LULESH 2.0. The code snippet shows a loop over nodes  $i$  from 0 to  $N-1$ . The variables  $xdd(i)$ ,  $ydd(i)$ , and  $zdd(i)$  represent acceleration components,  $fx(i)$ ,  $fy(i)$ , and  $fz(i)$  represent force components, and  $nodalMass(i)$  represents the mass of the node. Annotations highlight the single assignment nature of the variables:

- acceleration**: Points to  $xdd(i)$ ,  $ydd(i)$ , and  $zdd(i)$ .
- Dimensions**: Points to the index  $i$  in  $xdd(i)$ ,  $ydd(i)$ , and  $zdd(i)$ .
- force**: Points to  $fx(i)$ ,  $fy(i)$ , and  $fz(i)$ .
- mass**: Points to  $nodalMass(i)$ .
- Nodes**: Points to the loop variable  $i$  and the constant  $N$ .

# Single Assignment Example

## Acceleration calculation in LULESH 2.0:

```
for (Index_t i = 0; i < N; ++i) {  
    domain.xdd(i) = domain.fx(i) / domain.nodalMass(i);  
    domain.ydd(i) = domain.fy(i) / domain.nodalMass(i);  
    domain.zdd(i) = domain.fz(i) / domain.nodalMass(i);  
}  
    ↑           ↑           ↑  
acceleration  force      mass  
    ↓           ↓           ↓  
domain.ddd() [Nodes] [Dim] <=<= domain.fd() / domain.nodalMass();
```

# Single Assignment Example

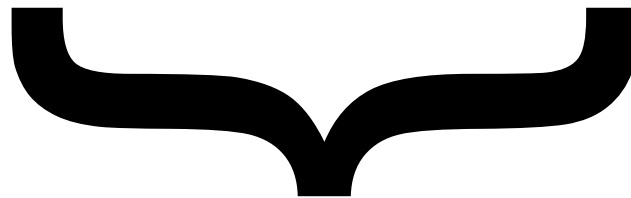
How it works

```
domain.ddd()[Nodes][Dim] <=<= domain.fd() / domain.nodalMass();
```



PuffinLhs<...>

PuffinExpression<PuffinDivide<...>, ...>



PuffinAssignment<...> (Immediately executes)

# Multiple Assignment Example

Plus temporary values and summation

## Update of volume derivative and strains in LULESH 2.0:

```
for( Index_t k=0 ; k<E ; ++k ) {  
    Real_t vdov = domain.dxx(k) + domain.dyy(k) + domain.dzz(k) ;  
    Temp value → Real_t vdovthird = vdov/Real_t(3.0) ;  
  
    domain.vdov(k) = vdov ; ← Volume derivative  
    Strains {  
        domain.dxx(k) -= vdovthird ;  
        domain.dyy(k) -= vdovthird ;  
        domain.dzz(k) -= vdovthird ;  
    }  
}
```

# Multiple Assignment Example

Plus temporary values and summation

## Update of volume derivative and strains in LULESH 2.0:

```
for( Index_t k=0 ; k<E ; ++k ) {
  Real_t vdov = domain.dxx(k) + domain.dyy(k) + domain.dzz(k) ;
  Temp value → Real_t vdovthird = vdov/Real_t(3.0) ;

  domain.vdov(k) = vdov ; ← Volume derivative
  Strains {
    domain.dxx(k) -= vdovthird ;
    domain.dyy(k) -= vdovthird ;
    domain.dzz(k) -= vdovthird ;
  }
}
```

Elements →

Dimensions ↓

sum\_over(Dim, domain.strains())

# Multiple Assignment Example

Plus temporary values and summation

## Update of volume derivative and strains in LULESH 2.0:

```
ScalarValue vdovthird;
```

```
puffin_foreach(Elms)
```

```
    (domain.vdov()           |= sum_over(Dim, domain.strains()))
```

```
    (vdovthird               |= domain.vdov() / 3.0)
```

```
    (domain.strains()[Dim]   |= domain.strains() - vdovthird)
```

```
    .execute();
```

# Multiple Assignment Example

How it works

```
puffin_foreach(Elems) ← Foreach Functor  
    (domain.vdov()      |= ...) ← PuffinAssignment<...>  
    (vdovthird         |= ...) ← PuffinAssignment<...>  
    (domain.strains() [Dim] |= ...) ← PuffinAssignment<...>  
    .execute();
```



# Multiple Assignment Example

How it works

```
puffin_foreach(Elems)
```

```
(domain.vdov()      |= ...)
```

```
(vdovthird          |= ...)
```

```
(domain.strains() [Dim] |= ...)
```

```
.execute();
```

}

Foreach Functor (1 assignment)

# Multiple Assignment Example

How it works

```
puffin_foreach(Elems)
```

```
  (domain.vdov()           |= ...)
```

```
  (vdovthird              |= ...)
```

```
  (domain.strains()[Dim]  |= ...)
```

```
  .execute();
```



Foreach Functor (2 assignments)

# Multiple Assignment Example

How it works

```
puffin_foreach(Elems)
```

```
(domain.vdov()      |= ...)
```

```
(vdovthird          |= ...)
```

```
(domain.strains() [Dim] |= ...)
```

```
.execute();
```



Foreach Functor (3 assignments)



Execution of all assignments happens in a single loop within execute() call.

# Indirect Array Example

## Start of EOS calculation in LULESH 2.0:

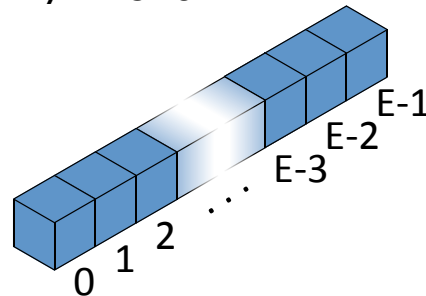
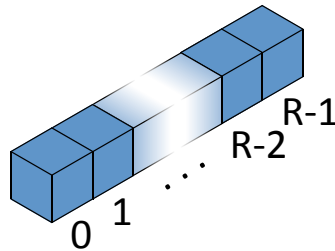
```
for (Index_t i = 0; i < domain.regElemSize(r) ; ++i) {  
    Index_t elem = domain.regElemList(r)[i]; ← Region  
    Real_t vchalf ;                               indirection  
    compression[i] = Real_t(1.) / vnewc[elem] - Real_t(1.);  
    vchalf          = vnewc[elem] - delvc[i] * Real_t(.5);  
    compHalfStep[i] = Real_t(1.) / vchalf - Real_t(1.);  
}
```

# Indirect Array Example

## Start of EOS calculation in LULESH 2.0:

```
Element
for (Index_t i = 0; i < domain.regElemSize(r); ++i) {
  Index_t elem = domain.regElemList(r)[i];
  Real_t vchalf;
  compression[i] = Real_t(1.) / vnewc[elem] - Real_t(1.);
  vchalf = vnewc[elem] - delvc[elem] * Real_t(.5);
  compHalfStep[i] = Real_t(1.) / vchalf - Real_t(1.);
}
```

Annotations in the code:  
- `domain.regElemSize(r)` is circled in orange. An arrow labeled "Current region" points to it.  
- `domain.regElemList(r)[i]` is circled in green. An arrow labeled "Region indirection" points to it.  
- `i` in `compression[i]` and `compHalfStep[i]` is circled in orange.  
- `elem` in `vnewc[elem]` and `delvc[elem]` is circled in green.



# Indirect Array Example

## Definition of region aspect and array, related to ElemAspect:

```
typedef PuffinAspect<3, -1, PuffinStyleRelatedArray<ElemAspect> >  
    SingleRegionAspect;
```

```
typedef PuffinArray<SingleRegionAspect>  
    SingleRegionArray;
```

## Based on $r$ , an aspect for the current region (CurReg) can be instantiated:

```
SingleRegionAspect CurReg(domain.regElemSize(r),  
                           domain.regElemList(r));
```

# Indirect Array Example

## Start of EOS calculation in LULESH 2.0:

```
ElemProvidedArray vnewc_p      (Elems, vnewc);  
ElemProvidedArray delvc_p      (Elems, delvc);  
SingleRegionArray compression (CurReg);  
SingleRegionArray compHalfStep(CurReg);  
ScalarValue      vchalf;
```

```
puffin_foreach(CurReg)  
  (compression   |= 1.0      / vnewc_p - 1.0)  
  (vchalf        |= vnewc_p - delvc_p * 0.5)  
  (compHalfStep  |= 1.0      / vchalf  - 1.0)  
  .execute();
```

# Affiliation Example

## Update of force in LULESH 2.0 (scatter):

```
for( Index_t i=0; i<E; ++i ) {  
    const Index_t *elemToNode = domain.nodelist(i);  
  
    domain.fx(elemToNode[0]) += hgfx[0];  
    domain.fy(elemToNode[0]) += hgy[0];  
    domain.fz(elemToNode[0]) += hgfz[0];  
  
    //...  
  
    domain.fx(elemToNode[7]) += hgfx[7];  
    domain.fy(elemToNode[7]) += hgy[7];  
    domain.fz(elemToNode[7]) += hgfz[7];  
}
```



Element to node  
indirection



# Affiliation Example

## Update of force in LULESH 2.0 (scatter):

```
for( Index_t i=0; i<E; ++i ) {  
    const Index_t *elemToNode = domain.nodelist(i);  
  
    domain.fx(elemToNode[0]) += hgfx[0];  
    domain.fy(elemToNode[0]) += hgyf[0];  
    domain.fz(elemToNode[0]) += hg fz[0];  
  
    //...  
  
    domain.fx(elemToNode[7]) += hgfx[7];  
    domain.fy(elemToNode[7]) += hgyf[7];  
    domain.fz(elemToNode[7]) += hg fz[7];  
}
```

Elements

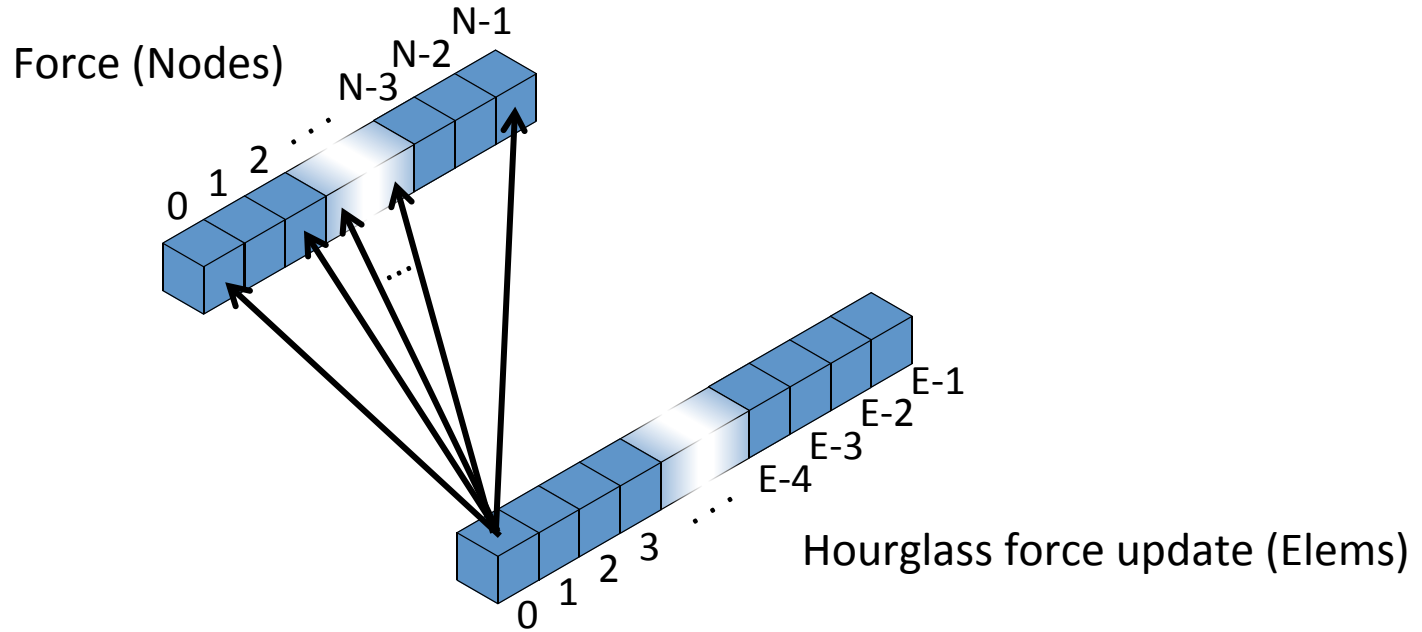
Element to node indirection

Element/Node indirection

Dimensions

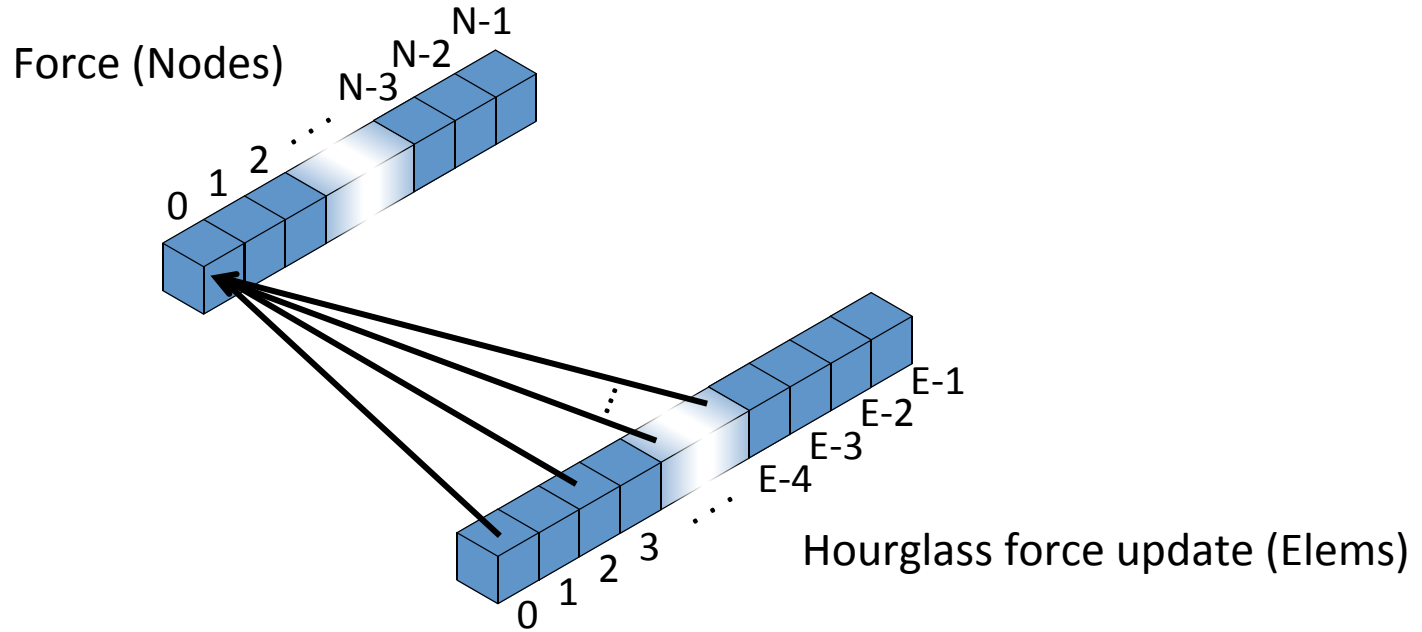
Corners

# Affiliation Example



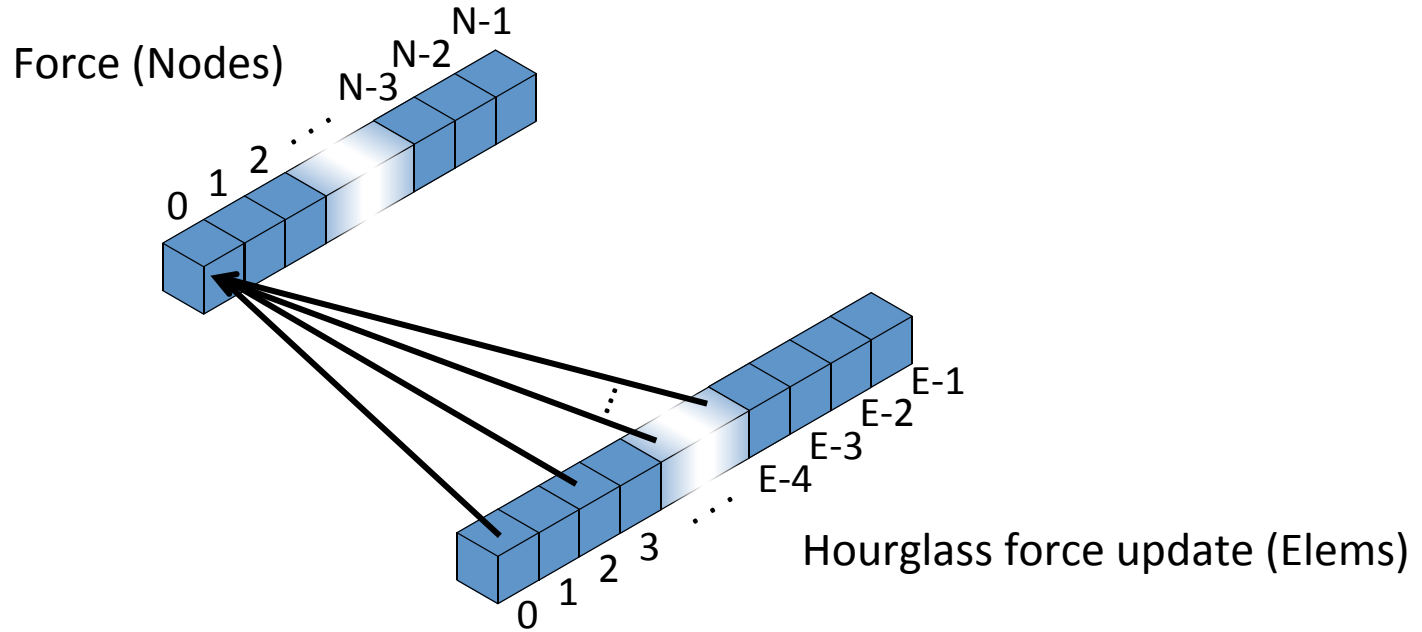
Scatter operation is efficient but not thread-safe.

# Affiliation Example



Gather operation is thread-safe.

# Affiliation Example



Gather operation is thread-safe.

# Affiliation Example

## Definition of corner aspect:

```
typedef PuffinAspect<4, 8, PuffinStyleFixedArray>  
    CornerAspect;
```

## Definition of array type for hgfd:

```
typedef PuffinArray<DimElemCornerAspects>  
    DimElemCornerArray;
```

## Instantiation of hgfd:

```
DimElemCornerArray hgfd_p(DimElemCorner);
```



# Affiliation Example

**Scatter version; ElemToNode affiliation used over a statement:**

```
puffin_foreach(Elems)
  (ElemToNode(domain.fd()[Dim] |= domain.fd() + hgfd_p))
  .execute();
```

**Gather version; NodeToElem affiliation summing over an expression:**

```
puffin_foreach(Nodes)(Dim)
  (domain.fd() |= domain.fd() + NodeToElem.sum(hgfd_p))
  .execute();
```

Current syntax is not final, but is sufficient for now.

# Puffin version of LULESH 2.0

Puffin supports all but about 10 loops of LULESH 2.0  
Remaining loops require “whole-aspect” calculations

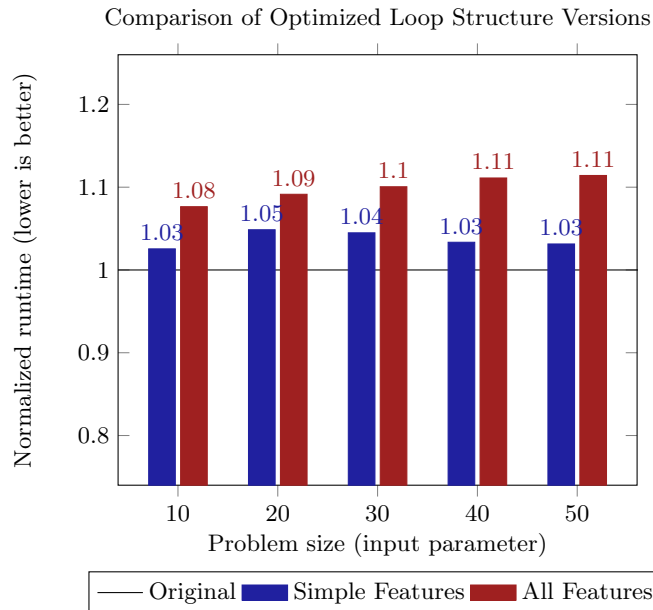
Puffin slows compile-time by 1.33x to 3x  
Mostly depends upon compile-time options

Puffin slows runtime performance by 5-11%  
Depends upon problem size, used features, and internal Puffin optimizations

Results can be maintained (down to the bit)  
Requires certain compiler flags (to maintain consistent 64-bit precision)



# LULESH 2.0 Performance Results



Puffin has roughly 5-11% runtime overhead.

# Summary

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Puffin is currently a prototype

Puffin can be adopted incrementally  
Useful for continuous use and maintaining results

Main benefit is low-overhead portable code with potential for performance  
Plan to support single-thread CPU, multi-thread CPU, GPU, and Xeon Phi

